## Spring 2020 Computer Architecture Ph.D. Qualifying Exam

## [30pts] 1. Performance Analysis

Many modern out-of-order processor cores can issue up to 4 instructions per cycle to their functional core units, which gives a theoretical peak CPI (cycles per instruction) of 0.25 (4 inst/cycle). In this problem we have such a CPU core, with the following parameters:

- "Perfect" no-stall CPI: 0.25 (i.e. 4 instructions/cycle)
- Branch misprediction penalty: 6 cycles
- Instruction cache miss penalty: 8 cycles
- Data cache read miss penalty: 8 cycles
- Data cache write miss penalty: 12 cycles

Our program's dynamic instruction mix is:

| Instruction class | Mix \% |
| :--- | :--- |
| Arithmetic + Logical | 60 |
| Load | 15 |
| Store | 5 |
| Branch/Jump | 20 |

Note that the only instructions that can perform memory data accesses are the load (read) and store (write) instructions.
[20pts] A. With a branch prediction accuracy of $95 \%$ (over all conditional and unconditional branches/jumps), an I-cache hit rate of $98 \%$, a D-cache hit rate of $90 \%$, and with $20 \%$ of the D-cache misses being write operations, what is the actual achieved average CPI?

Base CPI is 0.25
I-cache miss penalty is (1.0-0.98)*8 = .02*8 = . 16 CPI for all instructions
Branch mispredict penalty is $0.05^{*} .20^{*} 6=.06$ CPI
D-cache loads miss penalty is . $1^{*} .8^{*} .15^{*} 8=.096 \mathrm{CPI}$
D-cache stores miss penalty is . $1^{*} .2^{*} .05^{*} 12=.012 \mathrm{CPI}$
So total actual CPI is $0.5+.16+.03+.128+.024=0.578$ CPI
[10pts] B. Suppose that when we actually run and measure our program's performance, the CPI that is achieved ends up being 1.5 X what you calculated in part A . What would your explanation for this be? (Hint: consider potential hazards)
(Not sure if I should give the hint) Apart from the basic architectural delays for cache misses and branch mispredicts, the instructions themselves have data dependencies between them (data hazards), and with a pretty wide issue width ( 4 instructions), it is highly unlikely that forwarding could alleviate all of the data hazards. So instructions have to wait in queues for their data to be available, and this slows down the program.

## [40pts] 2. Branching and Pipelining

The main loop for a not-very-secure encryption algorithm might look like (in $\mathrm{C} / \mathrm{C}++$ ):

```
// p is int pointer, initialized to beginning of array (data to be encrypted)
// end is int pointer, initialized to array end plus 4 (value to stop p at)
// seed is the encryption code (hash value of the password)
// block is block size (also derived from password)
lastv = seed;
count = 0;
while (p != end)
{
    *p = *p ^ lastv;
    count++;
    lastv = *p;
    if (count % block == 0)
        lastv = seed;
    p++;
}
```

The algorithm uses exclusive-or chaining for a block size, then restarts the chaining from the seed again. This gives two parameters to make it at least a tiny bit secure.

We have a CPU with a 5 -stage pipelined architecture whose basic datapath is shown in the figure following the text of this question. Its features are:

- The stages are: (1) instruction fetch; (2) instruction decode and register access; (3) execute; (4) data memory access; (5) register write back.
- For a memory read instruction, stage 3 computes the effective address, the actual read (4 bytes) is completed in stage 4, and stage 5 writes the value to the destination register.
- Forwarding of values can be done from either of the last two stages to the execute stage (as shown in the datapath diagram).
- A static prediction of branch taken (i.e., branch to label) is always applied for all branches. The branch target address is calculated in stage 2 (as shown on the datapath) and can be used to fetch the target instruction without any stalls. The actual branch decision for conditional branches is not made until stage three (using the ALU for comparison).
- Registers $\$ t 0$ to $\$ t 15$ are available for general use.
- The register \$zero is a synonym for the constant 0 (zero).
- The instructions we will use to implement the above loop are:

| add r1, r2, const | r1 = r2 + const |
| :---: | :---: |
| xor r1, r2, r3 | $\mathrm{r} 1=\mathrm{r})^{\text {^ r3 }}$ |
| mod r1, r2, r3 | r1 = r2 \% r3 |
| mov r1, r2 | r1 = r2 |
| bne r1, r2, label | if (r1 ! = r2) goto label |
| sw const(r1), r2 | MEM[r1+const] = r2 |
| lw r1, const(r2) | r1 = MEM[r2+const] |

(note that the 'sw' and 'lw' instructions store and load words (4 bytes)

The translation of the C program (loop only) into assembly language is:

```
    # assume $t1 holds p, $t2 holds end, $t3 holds seed,
    # assume $t4 holds lastv, $t5 holds count, $t6 holds block size
    # assume $t1-$t5 are already initialized
    # $t0 will be used to hold temp vals: *p and mod result
    jmp L0 # start down at loop condition
L2: lw $t0, 0($t1) # label L2 is top of loop body
xor $t0, $t0, $t4
sw 0($t1), $t0
add $t5, $t5, 1
mov $t4, $t0
mod $t0, $t5, $t6
bne $t0, $zero, L1
mov $t4, $t3
L1: add $t1, $t1, 4
L0: bne $t1, $t2, L2
# rest of program below loop continues here
```

| Instructions | C1 | C2 | C3 | C4 | C5 | C6 | C7 | C8 | C9 | C10 | C11 | C12 | C13 | C14 | C15 | C16 | C17 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{array}{\|l} \text { L2: lw \$t0, } \\ 0(\$ \mathrm{t} 1) \end{array}$ | FE | REG | EX | MEM | WB |  |  |  |  |  |  |  |  |  |  |  |  |
| xor \$t0, \$t0, \$t4 |  | FE | REG | (bub) | EX | MEM | WB |  |  |  |  |  |  |  |  |  |  |
| sw 0(\$t1), \$t0 |  |  | FE | (bub) | REG | EX | MEM | WB |  |  |  |  |  |  |  |  |  |
| add \$t5, \$t5, 1 |  |  |  |  | FE | REG | EX | MEM | WB |  |  |  |  |  |  |  |  |
| mov \$t4, \$t0 |  |  |  |  |  | FE | REG | EX | MEM | WB |  |  |  |  |  |  |  |
| $\begin{aligned} & \bmod \$ \mathrm{t} 0, \$ \mathrm{t} 5, \\ & \$ \mathrm{t} 6 \end{aligned}$ |  |  |  |  |  |  | FE | REG | EX | MEM | WB |  |  |  |  |  |  |
| $\begin{aligned} & \text { bne \$t0, \$zero, } \\ & \text { L1 } \end{aligned}$ |  |  |  |  |  |  |  | FE | REG | EX | MEM | WB |  |  |  |  |  |
| mov \$t4, \$t3 |  |  |  |  |  |  |  |  |  |  | FE | REG | EX | MEM | WB |  |  |
| $\begin{aligned} & \text { L1: add \$t1, } \\ & \$ \mathrm{t} 1,4 \end{aligned}$ |  |  |  |  |  |  |  |  | (FE) | (REG) |  | FE | REG | EX | MEM | WB |  |
| $\begin{aligned} & \text { L0: bne \$t1, } \\ & \text { \$t2, L2 } \end{aligned}$ |  |  |  |  |  |  |  |  |  |  |  |  | FE | REG | EX | MEM | WB |

[20pts] A. Fill in the pipelined execution of one iteration of the loop body, cycle by cycle, in the table above. Assume that the loop has iterated at least once before, and that for this iteration the modulus result is equal to zero (a block has ended). Do not erase, but just X out so it is visible, any speculative execution that needs to be thrown away due to an incorrect branch prediction.

Table is filled in; the three entries in parentheses are speculative work that is thrown away once the misprediction on the branch is realized. Bottom-of-loop branch will predict taken and so will not stall.
[10pts] B. Describe all instances of forwarding that occur in your answer for part A.
Five: lw->xor (even with stall); xor->sw; add->mod; mod->bne; add->bne
[5pts] C. Describe how a compiler could reorder the instructions to improve this loop's cycle time.
The first add could be moved above the xor to remove the stall bubble.
[5pts] D. If we have $1,000,000$ words of data and our block size is 100 , what is the average number of cycles per iteration of this loop, for that data?

In our table, the next iteration of the loop will start in C14, so our iteration is 13 cycles long. But iterations where the modulus is nonzero will only be 10 cycles long. so 99*10+13 $=1003$ cycles for 100 iterations, which is an average of 10.03 cycles per iteration.


## [30pts] 3. Cache and VM Access Simulation

For this problem we have a cache and virtual memory system of the following configuration:

- Addressing: 20-bit virtual and physical byte addresses (20 bits $==5$ hex digits)
- Cache configuration:
- Number of sets (indices): 256
- Associativity: 2-way
- Word size: 4 bytes
- Block (line) size: 4 words
- Replacement algorithm: LRU
- Virtual memory configuration:
- Page size: 4 Kilobytes (KB)
- TLB: 16 entries, fully associative
- VM/Cache interaction: cache is virtually indexed but physically tagged, with page coloring if needed
[5pts] A. What is the total data storage capacity of the cache, in bytes?
The block size is 16 bytes ( 4 words, 4 bytes each), and there are two blocks for each of the 256 entries because it is 2 -way set associative. So $16 * 2 * 256=8 K B$.
[5pts] B. Draw the layout of the caching fields that the address gets divided into, labeling each and indicating their size in bits. Your drawing should have the most significant bit to the left.

| 8 bits | 8 bits | 4 bits |
| :--- | :--- | :--- |
| Tag | Index | Block+word offset |

[5pts] C. Draw the layout of the VM paging fields that the address gets divided into, labeling each and indicating their size in bits. Your drawing should have the most significant bit to the left.

| 8 bits | 12 bits |
| :--- | :--- |
| Page Number | Page offset |

[15pts] D. Assuming the cache is empty (all entries are invalid), provide a sequence of three memory reads (of words) that will cause at least one eviction to occur. All addresses you choose must cause hits in the TLB below. Show the cache set(s) accessed (by index) and the tags that are stored for each block (line).

TLB:

| Virtual PN | Physical PN |
| :--- | :--- |
| A5 | 81 |
| 6D | B9 |
| 91 | 2D |

Answer will have to just pick three addresses whose virtual page numbers are in the TLB and whose index bits select the same cache set, and that are not part of the same cache block. The third one will cause an eviction.

